



SRI MUTHUKUMARAN INSTITUTE OF TECHNOLOGY

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DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING

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YEAR: IV

SEM: VII

UNITI:-INTRODUCTION TO ANTENNA AND MICROWAVE SYSTEMS

PART-A

1. Define microwave.

Microwaves are electromagnetic waves (EM) with wavelength ranging from 1cm to 1mm. The corresponding frequency range is 1 GHz to 300GHz. Therefore, signals of high frequencies have relatively short wavelengths, hence the name “micro” waves.

2. What are the major bands available in microwave frequencies?

The microwave frequencies span the following three major bands at the highest end of RF spectrum.

- Ultra High Frequency (UHF) 0.3 to 3 GHz.
- Super High Frequency (SHF) 3 to 30 GHz.
- Extra High Frequency (EHF) 30 to 300 GHz.

3. Enumerate the basic advantages of microwaves.)

- Fewer repeaters are sufficient for amplification.
- Minimal crosstalk exists between voice channels.
- Increased reliability and less maintenance.
- Increased bandwidth availability

4. Write the applications of microwaves. (

- Microwave becomes a very powerful tool in microwave radio spectroscopy for analysis.
- Microwave landing system (MLS), used to guide aircraft to land safely at airports.
- Special microwave equipment known as diathermy machines are used in medicine for heating body muscles and tissues without hurting the skin.
- Microwave ovens are a common appliance in most kitchens today.

5. Define Antenna. (R)

Antenna is a structure associated with the region of transition between guided wave and free space wave and vice versa

6. Define an Isotropic Antenna. (R)(Nov /Dec '14)(May/June'06)

An Isotropic Antenna is the one which radiate energy uniformly in all directions.

7. What are dB and dBd? Write their significances? (R)(Nov/Dec'13)

dB_i – Decibel with respect to isotropic antenna. dB_d– decibel with respect to dipole antenna. dB_i is a measurement that compares the gain of an antenna with respect to an isotropic radiator. dB_d compares the gain of an antenna to the gain of a reference dipole antenna.

8. Differentiate radian and Steradian. (U)(Nov/Dec'17)

Radian	Steradian
Measurement of planar angle is radian.	Measurement of solid angle is Steradian.
1 Circle contains 2π radians	1 Sphere contains 4π Steradians.
$1 \text{ Sr} = 1 \text{ rad}^2$	

9. Define Radiation pattern. (R)

Antenna Radiation pattern is a 3 dimensional graph which shows the variation in actual field strength of EMF at all points which are at equal distance from the antenna.

10. What are Δ and Θ pattern in antenna radiation pattern? (R) (Nov/Dec'13)

and farfield. (R)(May/June'07)/(Apr/May'15)

Induction field (Near field): The field which predominates at the points closer to the current element where r is small is known as induction field. The near field is inversely proportional to square of the distance ($1/r^2$). It is of less importance.

Radiation field (Far field): The radiation field is farfield and it varies inversely with distance ($1/r$). This field contributes to the flow of energy away from the source. This radiation field or farfield is of great importance at large distance.

14. The radial component of the radiated power density of an antenna is given by

$W_{rad} = a_r A_0 \sin^2 \theta / r^2$ (W/m²). Determine the total radiated power. (R)

(Nov/Dec '16)

$$U_{rad} = \frac{W_{rad}}{A} = \frac{a_r A_0 \sin^2 \theta}{r^2}$$

$$P_{rad} = \int U_{rad} dA = \int \frac{a_r A_0 \sin^2 \theta}{r^2} r^2 \sin \theta d\theta d\phi$$

$$P_{rad} = a_r A_0 \int_0^{2\pi} \int_0^\pi \sin^3 \theta d\theta d\phi$$

$$P_{rad} = a_r A_0 \int_0^{2\pi} d\phi \int_0^\pi \sin^3 \theta d\theta$$

$$P_{rad} = a_r A_0 (2\pi) \left[-\cos \theta + \frac{1}{3} \cos^3 \theta \right]_0^\pi$$

$$P_{rad} = a_r A_0 (2\pi) \left[-(-1) + \frac{1}{3}(-1)^3 - (-1 + \frac{1}{3}) \right]$$

$$P_{rad} = a_r A_0 (2\pi) \left[1 - \frac{1}{3} - 1 + \frac{1}{3} \right]$$

$$P_{rad} = a_r A_0 (2\pi) \left[\frac{2}{3} \right]$$

$$P_{rad} = \frac{4\pi}{3} a_r A_0$$

Watts

15. Define Radiation resistance of antenna. (R) (May/June'09)

Radiation resistance is defined as a 'Virtual resistance that does not exist physically but is a quantity coupling the antenna to distant regions of space via a transmission line'.

16. The radiation resistance of an antenna is 72Ω and loss resistance is 8Ω . What is the directivity (indB) if the power gain is 15. (R) (Nov/Dec'16)

$$\frac{R_r}{R_r + R_l} = 0.9$$

$$\frac{G}{D} = \frac{R_r R_l}{R_r + R_l} = 15 \times 0.9 = 16.67$$

$$D(\text{indB}) = 10 \log D = 10 \log 16.67 = 12.22 \text{ dB}$$

17. Write the importance of radiation resistance of an antenna. (R) (Apr'15)/(Apr'14)

21. Define Directivity of Antenna. (R) (May/June'12) & (Nov/Dec'09)

Directivity is defined as the ratio of Radiation intensity of test antenna in a given direction to radiation intensity of isotropic antenna. $D = U/U_0$

Where U = Radiation intensity of test antenna $U_0 = R_{\text{rad}}$

radiation intensity of Isotropic antenna

It is also expressed as $D = \frac{4\pi U}{P_{\text{rad}}}$

22. Define gain of an antenna. What is the relation between gain and aperture of an antenna? (R) (Nov/Dec '16)/(April/May'17)

Gain is defined as the ratio of Radiation intensity of test antenna in a given direction to radiation intensity of isotropic antenna, assuming same input power. $G = U/U_0$

Where U = Radiation intensity of test antenna

U_0 = Radiation intensity of Isotropic antenna

The relation between gain and aperture is, $G = \frac{4\pi A_e}{\lambda^2} \sin^2 \theta$ (U)

23. Distinguish between power gain and directive gain. (U) (Nov/Dec '14)

Both power gain and directive gain refers to the ratio of Radiation intensity of test antenna in a given direction to radiation intensity of isotropic antenna. But power gain is measured by considering same input power whereas directive gain is measured by considering radiated power.

24. What is front to back ratio? (R)

Front to Back Ratio (FBR) is defined as the ratio of power radiated in the desired direction to the power radiated in the opposite direction
ie. $FBR = \frac{\text{power radiated in desired direction}}{\text{power radiated in opposite direction}}$

28. Define Effective aperture of an antenna. (R) (May/June '12) & (Nov/Dec '12)

Effective aperture is defined as the ratio of power received at the antenna load terminal to the pointing vector (power density) of the incident wave. Its unit is W/m^2 .

29. What is the relationship between effective aperture and directivity? (R)

The relationship between effective aperture and directivity is $D = \frac{4\pi A_e}{\lambda^2} \sin^2 \theta$

30. What is the significance of aperture of an antenna? (R) (Apr/May '15)

Aperture of an antenna is a useful parameter that calculates the receive power of an antenna. It describes how much power is captured from a given plane wave.

31. Write the antenna field zones with the boundaries of an antenna under test. (R)

(Nov/Dec '04)

The spaces surrounding an antenna is divided into 3 regions.

They are a) Reactive near field

b) Radiation near field (Fresnel) and

c) Radiation far field (Fraunhofer)

The outer boundary of Reactive near field is at a distance $R <$

$0.62\sqrt{D^3/\lambda}$ The inner boundary of radiation near field (Fresnel) is given by

$R \approx 0.62 \sqrt{\frac{D^3}{\lambda}}$ and its outer boundary is $R < 2D^2/\lambda$

The inner boundary of far field is given by $R \geq$

$2D^2/\lambda$ Where, D = largest dimension of the antenna

λ = wavelength in meter

32. What do you mean by effective length of the antenna? (R)

The term effective length of an antenna represents the 'effectiveness of an antenna as radiator or collector of electromagnetic wave energy'. For a receiving antenna, it is defined as the ratio of induced voltage at the terminals of the receiving antenna under open circuit condition to the incident electric field strength E .

Effective length, l_e or $h = V/E$ (meter or wavelength)

33. What do you mean by self impedance? (R)

Self impedance is defined as the ratio of voltage to current at a pair of terminals.

$Z_{11} = R_{11} + jX_{11}$

where, R_{11} = Radiation resistance, X_{11} = Self reactance

34. What is mutual impedance? (R)

It is defined as the negative ratio of emf

induced in one antenna to the current flowing in the antenna.

Mutual Impedance, $Z_{21} = -V_{21}/I_1$ (or) $Z_{12} = -V_{12}/I_2$

35. What is Balun? (R)

A Balun is a device that joins a balanced line (one that has two conductors, with equal currents in opposite directions, such as a twisted pair cable) to an unbalanced line (one that has just one conductor and a ground, such as a coaxial cable). A typical use for a balun is in a television antenna. The term is derived by combining balanced and unbalanced.

PART-B

UNIT I INTRODUCTION TO MICROWAVE SYSTEMS AND ANTENNAS

1). Explain the electromagnetic spectrum and microwave frequency bands.

Electromagnetic spectrum:

Electromagnetic spectrum

Microwaves occupy a place in the electromagnetic spectrum with frequency above ordinary radio waves, and below infrared light.

Electromagnetic spectrum			
Name	Wavelength	Frequency (Hz)	Photon energy (eV)
Gamma ray	< 0.02 nm	> 15 EHz	> 62.1 keV
X-ray	0.01 nm – 10 nm	30 EHz – 30 PHz	124 keV – 124 eV
Ultraviolet	10 nm – 400 nm	30 PHz – 750 THz	124 eV – 3 eV
Visible light	390 nm – 750 nm	770 THz – 400 THz	3.2 eV – 1.7 eV
Infrared	750 nm – 1 mm	400 THz – 300 GHz	1.7 eV – 1.24 meV
Microwave	1 mm – 1 m	300 GHz – 300 MHz	1.24 meV – 1.24 μeV
Radio	1 m – 100 km	300 MHz – 3 kHz	1.24 μ eV – 12.4 feV

Microwave Frequency Bands:

Microwaves Frequency Bands

Band	Frequency range
HF Band	3 to 30 MHz
VHF Band	30 to 300 MHz
UHF Band	300 to 1000 MHz
L Band	1 to 2 GHz
S Band	2 to 4 GHz
C Band	4 to 8 GHz
X Band	8 to 12 GHz
Ku Band	12 to 18 GHz
K Band	18 to 27 GHz
Ka Band	27 to 40 GHz
V Band	40 to 75 GHz
W Band	75 to 110 GHz
mm Band	110 to 300 GHz

b) Explain the physical concepts of radiation.

Physical Concept of Radiation(Radiation Mechanism)

One of the first questions that may be asked concerning antennas would be “how is radiation accomplished?”

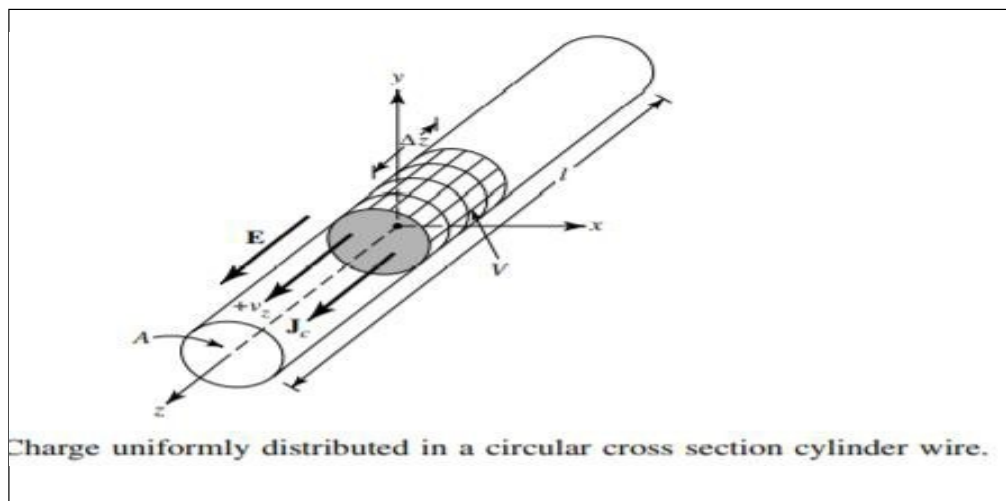
In other words, how are the electromagnetic fields generated by the source, contained and guided within the transmission line and antenna, and finally “detached” from the antenna to form a free-space wave?

Let us first examine some basic sources of radiation.

Radiation from Single Wire

Conducting wires are material whose prominent characteristic is the motion of electric charges and the creation of current flow.

Let us assume that an electric volume charge density, represented by q_v (coulombs/m³), is distributed uniformly in a circular wire of cross-sectional area A and volume V , as shown in Figure.



The total charge Q within volume V is moving in the z direction with a uniform velocity v_z (meters/sec). It can be shown that the current density J_z (amperes/m²) over the cross section of the wire is given by

$$J_z = q_v v_z \quad (1a)$$

If the wire is made of an ideal electric conductor, the current density J_s (amperes/m) resides on the surface of the wire and it is given by

$$J_s = q_s v_z \quad (1b)$$

where q_s (coulombs/m²) is the surface charge density.

If the wire is very thin (ideally zero radius), then the current in the wire can be represented by

$$I_z = q_l v_z \quad (1c)$$

where q_l (coulombs/m) is the charge per unit length. Instead of examining all three current densities, we will primarily concentrate on the very thin wire. The conclusions apply to all three.

If the current is time varying, then the derivative of the current of (1c) can be written as

$$dI_z/dt = q_l dv_z/dt = q_l a_z \quad (2)$$

where $dv_z/dt = a_z$ (meters/sec²) is the acceleration. If the wire is of length l , then (2) can be written as

$$l dI_z/dt = l q_l dv_z/dt = l q_l a_z \quad (3)$$

Equation (3) is the basic relation between current and charge, and it also serves as the fundamental relation of electromagnetic radiation.

It simply states that to create radiation, there must be a time-varying current or an acceleration (or deceleration) of charge. We usually refer to currents in time-harmonic applications while charge is most often mentioned in transients. To create charge acceleration (or deceleration) the wire must be curved, bent, discontinuous, or terminated. Periodic charge acceleration (or deceleration) or time-varying current is also created when charge is oscillating in a time-harmonic motion.

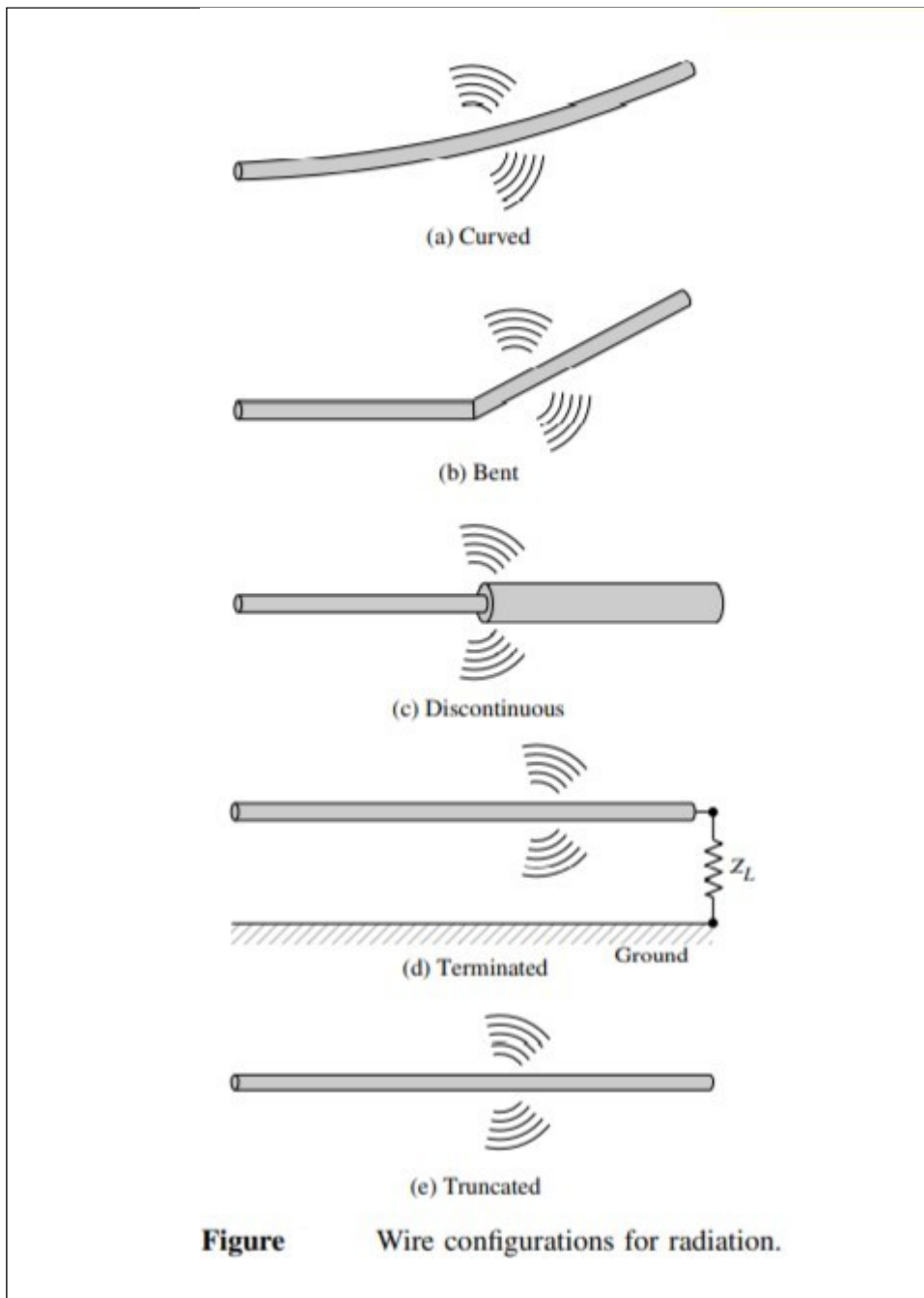
Important Conclusions:

- (i) If a charge is not moving, current is not created and there is no radiation.
- (ii) If charge is moving with a uniform velocity:
 - (a) There is no radiation if the wire is straight, and infinite in extent.
 - (b) There is radiation if the wire is curved, bent, discontinuous, terminated, or truncated, as shown in Figure
- (iii) If charge is oscillating in a time-motion, it radiates even if the wire is straight.

A qualitative understanding of the radiation mechanism may be obtained by considering a pulse source attached to an open-ended conducting wire, which may be connected to the ground through a discrete load at its open end, as shown in Figure (d).

When the wire is initially energized, the charges (free electrons) in the wire are set in motion by the electric lines of force created by the source. When charges are accelerated in the source-end of the wire and decelerated (negative acceleration with respect to original motion) during reflection from its end, it is suggested that radiated fields are produced at each end and along the remaining part of the wire.

Stronger radiation with a more broad frequency spectrum occurs if the pulses are of shorter or more compact duration while continuous time-harmonic oscillating charge produces, ideally, radiation of single frequency determined by the frequency of oscillation.



The acceleration of the charges is accomplished by the external source in which forces set the charges in motion and produce the associated field radiated. The deceleration of the charges at the end of the wire is accomplished by the internal (self) forces associated with the induced field due to the build up of charge concentration at the ends of the wire. The internal forces receive energy from the charge buildup as its velocity is reduced to zero at the ends of the wire. **Therefore, charge acceleration due to an exciting electric field and deceleration due to impedance discontinuities or smooth curves of the wire are mechanisms responsible for electromagnetic radiation.**

Radiation from Two-Wires

Let us consider a voltage source connected to a two-conductor transmission line which is connected to an antenna. This is shown in Figure. Applying a voltage across the two-conductor transmission line creates an electric field between the conductors. The electric field has associated with it electric lines of force which are tangent to the electric field at each point and their strength is proportional to the electric field intensity. The electric lines of force have a tendency to act on the free electrons (easily detachable from the atoms) associated with each conductor and force them to be displaced. The movement of the charges creates a current that in turn creates a magnetic field intensity. Associated with the magnetic field intensity are magnetic lines of force which are tangent to the magnetic field.

We have accepted that electric field lines start on positive charges and end on negative charges. They also can start on a positive charge and end at infinity, start at infinity and end on a negative charge, or form closed loops neither starting or ending on any charge. Magnetic field lines always form closed loops encircling current-carrying conductors because physically there are no magnetic charges.

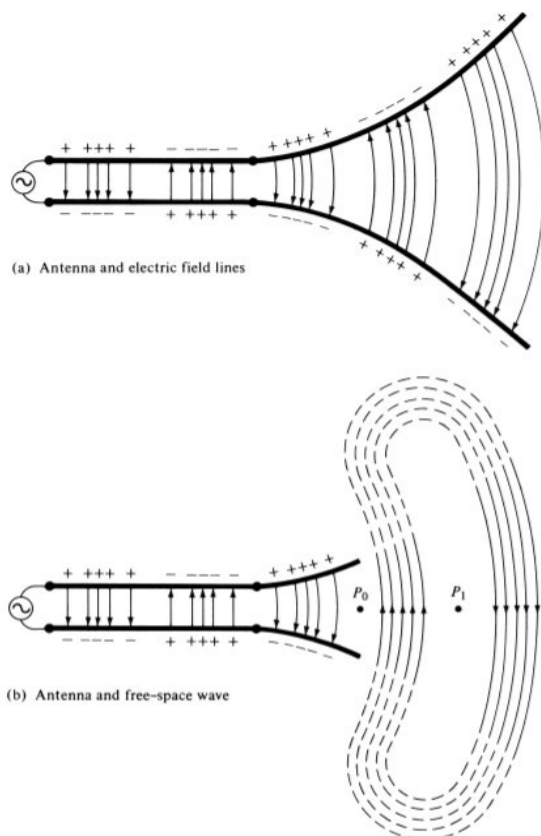


Figure Source, transmission line, antenna, and detachment of electric field lines.

The electric field lines drawn between the two conductors help to exhibit the distribution of charge. If we assume that the voltage source is sinusoidal, we expect the electric field between the conductors to also be sinusoidal with a period equal to that of the applied source. The relative magnitude of the electric field intensity is indicated by the density (bunching) of

the lines of force with the arrows showing the relative direction (positive or negative). The creation of time-varying electric and magnetic fields between the conductors forms electromagnetic waves which travel along the transmission line, as shown in Figure (a).

The electromagnetic waves enter the antenna and have associated with them electric charges and corresponding currents. If we remove part of the antenna structure, as shown in Figure(b), free-space waves can be formed by “connecting” the open ends of the electric lines (shown dashed).

The free-space waves are also periodic but a constant phase point P_0 moves outwardly with the speed of light and travels a distance of $\lambda/2$ (to P_1) in the time of one-half of a period. It has been shown that close to the antenna the constant phase point P_0 moves faster than the speed of light but approaches the speed of light at points far away from the antenna (analogous to phase velocity inside a rectangular waveguide).

free-space waves and water waves analogy

The question still unanswered is how the guided waves are detached from the antenna to create the free-space waves that are indicated as closed loops. Before we attempt to explain that, let us draw a parallel between the guided and free-space waves, and water waves created by the dropping of a pebble in a calm body of water or initiated in some other manner.

Once the disturbance in the water has been initiated, water waves are created which begin to travel outwardly. If the disturbance has been removed, the waves do not stop or extinguish themselves but continue their course of travel. If the disturbance persists, new waves are continuously created which lag in their travel behind the others. The same is true with the electromagnetic waves created by an electric disturbance.

If the initial electric disturbance by the source is of a short duration, the created electromagnetic waves travel inside the transmission line, then into the antenna, and finally are radiated as free-space waves, even if the electric source has ceased to exist (as was with the water waves and their generating disturbance). If the electric disturbance is of a continuous nature, electromagnetic waves exist continuously and follow in their travel behind the others. This is shown in Figure for a biconical antenna. When the electromagnetic waves are within the transmission line and antenna, their existence is associated with the presence of the charges inside the conductors. However, when the waves are radiated, they form closed loops and there are no charges to sustain their existence. This leads us to conclude that electric charges are required to excite the fields but are not needed to sustain them and may exist in their absence. This is in direct analogy to the water waves.

Isotropic, Directional, and Omnidirectional Patterns

An isotropic radiator is defined as “a hypothetical lossless antenna having equal radiation in all directions.” Although it is ideal and not physically realizable, it is often taken as a reference for expressing the directive properties of actual antennas.

A directional antenna is one “having the property of radiating or receiving electromagnetic waves more effectively in some direction than in others”. Example of antenna with directional radiation patterns is shown in Figure.

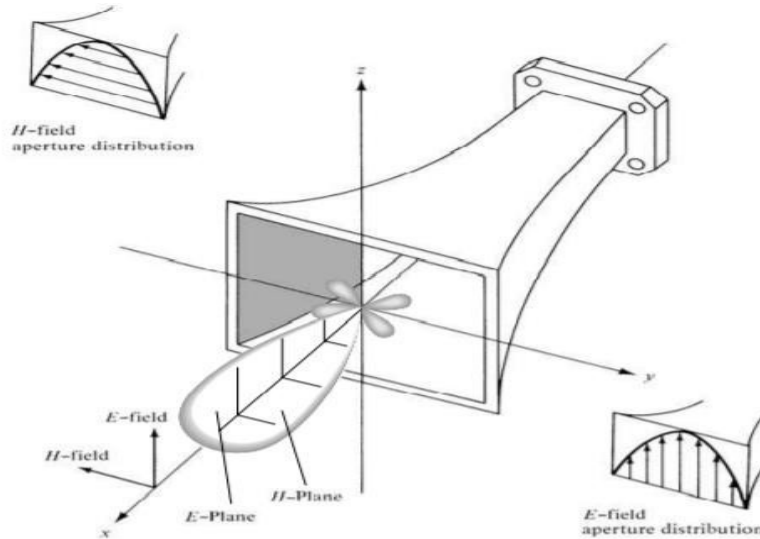


Figure . Principal E - and H -plane patterns for a pyramidal horn antenna.

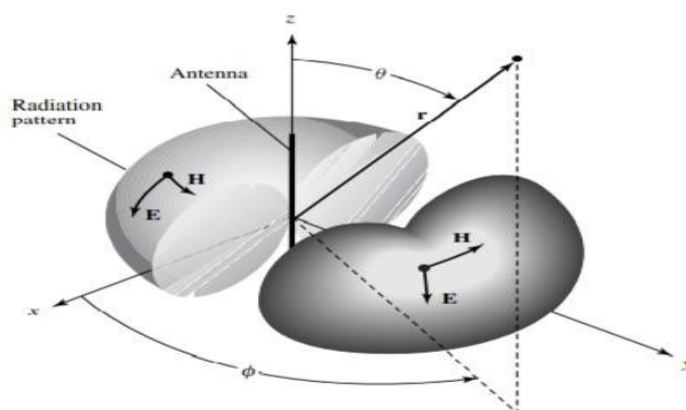


Figure . Omnidirectional antenna pattern.

2.(a) Explain the following antenna parameters.

Antenna near and far field (Field Regions of Antenna)

The spaces surrounding an antenna is usually subdivided into three regions:

- (a) reactive near-field,
- (b) radiating near-field (Fresnel) and
- (c) far-field (Fraunhofer) regions as shown in Figure.

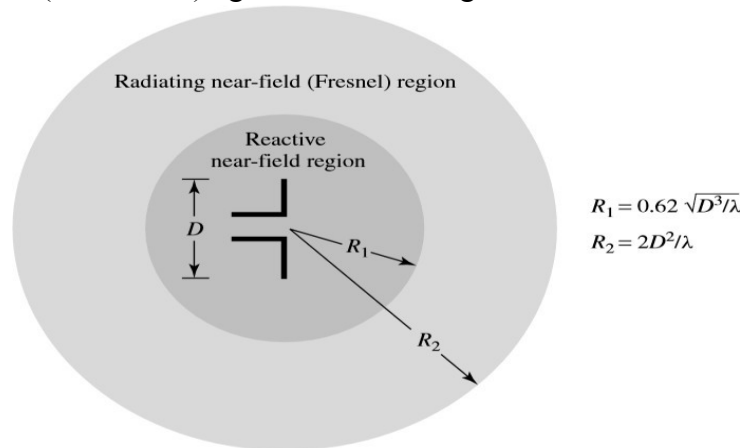


Figure 1.1 Field regions of an antenna.

These regions are so designated to identify the field structure in each. Although no abrupt changes in the field configurations are noted as the boundaries are crossed, there are distinct differences among them.

Reactive near-field region

Reactive near-field region is defined as “that portion of the near-field region immediately surrounding the antenna wherein the reactive field predominates.” For most antennas, the outer boundary of this region is commonly taken to exist at a distance $R <$

$0.62 \sqrt{\frac{D^3}{\lambda}}$ from the antenna surface, where λ is the wavelength and D is the largest dimension of the antenna. “For a very short dipole, or equivalent radiator, the outer boundary is commonly taken to exist at a distance $\lambda/2\pi$ from the antenna surface.”

Radiating near-field (Fresnel) region

Radiating near-field (Fresnel) region is defined as “that region of the field of an antenna between the reactive near-field region and the far-field region wherein radiation fields predominate and wherein the angular field distribution is dependent upon the distance from the antenna.

If the antenna has a maximum dimension that is not large compared to the wavelength, this region may not exist. For an antenna focused at infinity, the radiating near-field region is sometimes referred to as the Fresnel region on the basis of analogy to optical terminology. If the antenna has a maximum overall dimension which is very small compared to the wavelength,

“this field region may not exist.” The inner boundary is taken to be the distance $R \geq 0.62 \sqrt{\frac{D^3}{\lambda}}$ and the outer boundary the distance $R < 2D^2/\lambda$ where D is the largest dimension of the antenna. This criterion is based on a maximum phase error of $\pi/8$. In this region the field pattern is, in general, a function of the radial distance and the radial field component may be appreciable.

*To be valid, D must also be large compared to the wavelength ($D > \lambda$)

Far-field(Fraunhofer)region

Far-field(Fraunhofer)region is defined as “that region of the field of an antenna where the angular field distribution is essentially independent of the distance from the antenna. If the antenna has a maximum overall dimension D , the far-field region is commonly taken to exist at distances greater than $2D^2/\lambda$ from the antenna, λ being the wavelength.

The far-field patterns of certain antennas, such as multibeam reflector antennas, are sensitive to variations in phase over their apertures. For these antennas $2D^2/\lambda$ may be inadequate. In physical media, if the antenna has a maximum overall dimension, D , which is large compared to $\pi/|\gamma|$, the far-field region can be taken to begin approximately at a distance equal to $|\gamma| D^2/\pi$ from the antenna, γ being the propagation constant in the medium.

For an antenna focused at infinity, the far-field region is sometimes referred to as the Fraunhofer region on the basis of analogy to optical terminology.” In this region, the field components are essentially transverse and the angular distribution is independent of the radial distance where the measurements are made. The inner boundary is taken to be the radial distance $R = 2D^2/\lambda$ and the outer one at infinity.

The amplitude pattern of an antenna in different regions

The amplitude pattern of an antenna, as the observation distance is varied from the reactive near field to the far field, changes in shape because of variation of the fields, both magnitude and phase.

A typical progression of the shape of an antenna, with the largest dimension D , is shown in Figure. It is apparent that in the reactive near field region the pattern is more spread out and nearly uniform, with slight variations. As the observation is moved to the radiating near-field region (Fresnel), the pattern begins to smooth and form lobes. In the far-field region (Fraunhofer), the pattern is well formed, usually consisting of few minor lobes and one, or more, major lobes.

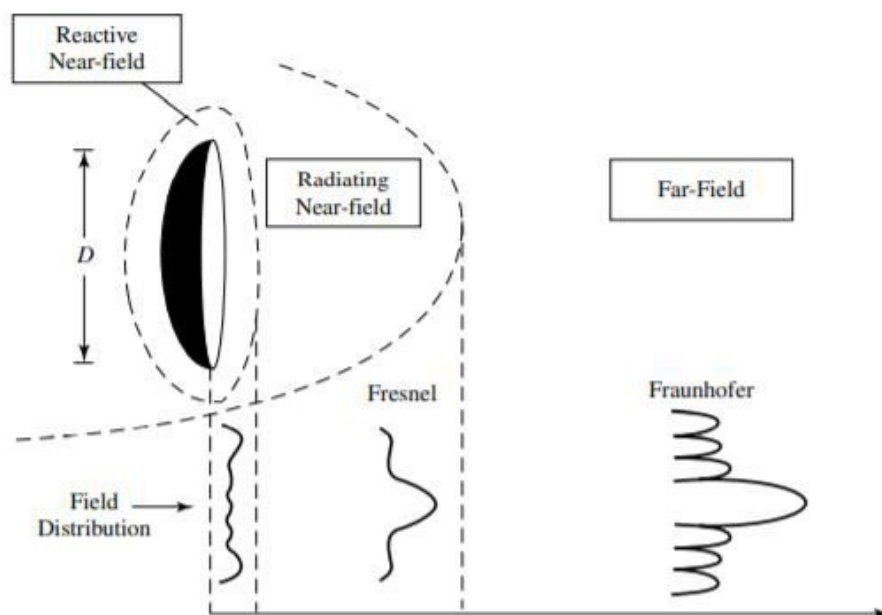


Figure: Typical changes of antenna amplitude pattern shape from reactive near field toward the far field

3.Explain and detail about following antenna parameters.

AntennaParameters

(a) Radiation pattern.

The radiation pattern of an antenna is a plot of the magnitude of the far-zone field strength versus position around the antenna, at a fixed distance from the antenna.

Thus the radiation pattern can be plotted from the pattern function $F_{\theta}(\theta, \phi)$ or $F_{\phi}(\theta, \phi)$, versus either the angle θ (for an elevation plane pattern) or the angle ϕ (for an azimuthal plane pattern). The choice of plotting either F_{θ} or F_{ϕ} is dependent on the polarization of the antenna.

(b) main lobe, side lobe, minor lobe and back lobe with reference to antenna radiation pattern.

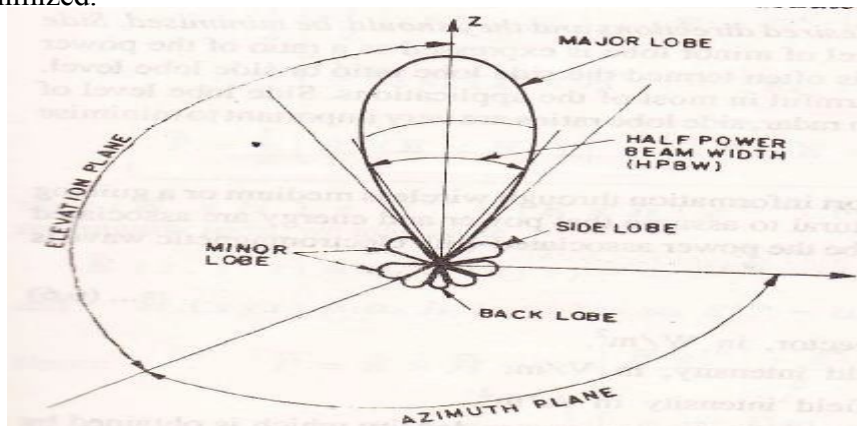
Major Lobe: Major lobe is also called as main beam and is defined as “the radiation lobe containing the direction of maximum radiation”. In some antennas, there may be more than one major lobe.

Minor lobe: All the lobes except the major lobes are called minor lobe.

Sidelobe: A sidelobe is adjacent to the main lobe.

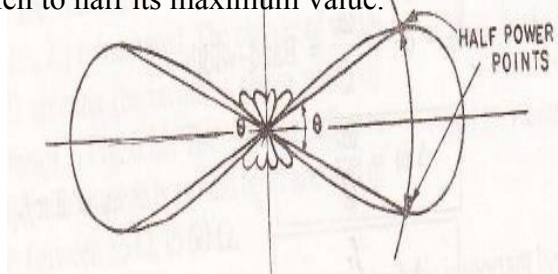
Backlobe: Normally refers to a minor lobe that occupies the hemisphere in a direction opposite to that of the major (main) lobe .

- Minor lobes normally represent radiation in undesired directions and they should be minimized.



(c) Half Power Beam Width (HPBW) of an antenna.

Half Power Beam Width is a measure of directivity of an antenna. It is an angular width in degrees, measured on the radiation pattern (main lobe) between points where the radiated power has fallen to half its maximum value.



(d) beam solidangle

The beam area or beam solid angle Ω_A for an antenna is given by integral of the normalized power pattern over a sphere.

$$\Omega_A = \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} P_n(\theta, \phi) \sin\theta \, d\theta \, d\phi \quad \text{steradian}$$

$$P_n(\theta, \phi) = \frac{P(\theta, \phi)}{P_{max}} \quad \text{Normalize power pattern}$$

Beam solid angle is also given approximately by

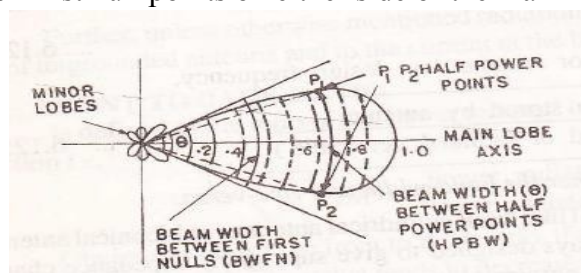
$$\Omega_A \approx \Delta\theta_{HP} \Delta\phi_{HP} \quad \text{steradian}$$

$$\Delta\theta_{HP} = \text{HPBW in } \vec{E} \text{ plane or } \theta \text{ plane}$$

$$\Delta\phi_{HP} = \text{HPBW in } \vec{H} \text{ plane or } \phi \text{ plane}$$

(e) Beam Width between First Null

Beam width between first null (BWFN) is the angular width in degrees, measured on the radiation pattern between first null points on either side of the main lobe.



(f) Radiation Intensity

Radiation intensity $U(\theta, \phi)$ in given direction is defined as the power per unit solid angle in that direction.

- The power radiated per unit area in any direction is given by pointing vector P.
- For distant field for which E and H are orthogonal in a plane normal to the radius vector,

The power flow per unit area is given by

$$P = \frac{E^2}{\eta} \quad \text{watts/sqm}$$

- There are r^2 square meters of surface area per unit solid angle (or steradian).
- $U(\theta, \phi) = r^2 P = \frac{r^2 E^2}{\eta} \quad \text{watts/unit solid angle}$

The radiation intensity gives the variation in radiated power versus position around the antenna. We can find the total power radiated by the antenna by integrating the Poynting vector over the surface of a sphere that encloses the antenna. This is equivalent to integrating the radiation intensity over a unit sphere.

$$P_{rad} = \text{Power radiated} = \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi} U(\theta, \phi) \sin\theta \, d\theta \, d\phi$$

(g) Directivity of an antenna

The directivity (D) of an antenna is defined as the ratio of the maximum value of the power radiated per unit solid angle to the average power radiated per unit solid angle. That is, directivity is ratio of the maximum radiation intensity in the main beam to the average radiation intensity over all space.

$$D = \frac{U_{max}}{U_{avg}} = \frac{P_{rad}}{P_{rad}} = \frac{4\pi U_{max}}{\int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi} U(\theta, \phi) \sin\theta d\theta d\phi}$$

Thus, the directivity measures how intensely the antenna radiates in its preferred direction than an isotropic radiator would when fed with the same total power.

Directivity is a dimensionless ratio of power, and is usually expressed in dB as $D(\text{dB}) = 10 \log(D)$

directivity of isotropic radiator:

An isotropic radiator is a hypothetical lossless radiator having equal radiation in all directions.

$U(\theta, \phi) = 1$ for isotropic antenna. Applying the integral identity, $\int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi} \sin\theta d\theta d\phi = 4\pi$, we have,

$$D = \frac{4\pi U_{max}}{\int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi} U(\theta, \phi) \sin\theta d\theta d\phi} = 1$$

The directivity of an isotropic antenna is $D = 1$, or 0 dB.

Relationship between Directivity and beamwidth

Beamwidth and directivity are both measures of the focusing ability of an antenna: an antenna pattern with a narrow main beam will have a high directivity, while a pattern with a wide beam will have a lower directivity.

Approximate relation between beam width and directivity that apply with reasonable accuracy for antennas with pencil beam patterns is the following:

$D \cong \frac{32,000}{\theta_1 \theta_2}$ where θ_1 and θ_2 are the beamwidths in two orthogonal planes of the main beam, in degrees. This approximation does not work well for omnidirectional patterns because there is a well-defined main beam in only one plane for such patterns.

(h) radiation efficiency of antenna

Radiation efficiency of an antenna is defined as the ratio of the radiated output power to the supplied input power.

$$\eta_{rad} = \frac{P_{rad}}{P_{in}} = \frac{P_{in} - P_{loss}}{P_{in}} = 1 - \frac{P_{loss}}{P_{in}}$$

where P_{rad} is the power radiated by the antenna, P_{in} is the power supplied to the input of the antenna, and P_{loss} is the power lost in the antenna (dissipative losses) due to metal conductivity or dielectric loss within the antenna.

(i) Gain of an antenna

The gain of the antenna is closely related to the directivity, it is a measure that takes into account the efficiency of the antenna as well as its directional capabilities.

Antenna gain is defined as the product of directivity and efficiency:

$$Gain = G = \eta_{rad} \times D.$$

Thus, gain is always less than or equal to directivity.

(j) Aperture efficiency

Aperture efficiency is defined as the ratio of the actual directivity of an aperture antenna to the maximum directivity of aperture antenna.

The maximum directivity that can be obtained from an electrically large aperture of area A is given as, $D_{max} = \frac{4\pi A}{\lambda^2}$

$$\eta_{ap} = \text{aperture efficiency} = \frac{D}{D_{max}}$$

(k) Effective aperture area

Received power is proportional to the power density, or Poynting vector, of the incident wave. Since the Poynting vector has dimensions of W/m^2 , and the received power, P_r , has dimensions of W , the proportionality constant must have units of area.

$$\text{We have, } P_r = A_e \times S_{avg}$$

where A_e is defined as the effective aperture area of the receive antenna. The effective aperture area has dimensions of m^2 , and can be interpreted as the “capture area” of a receive antenna, intercepting part of the incident power density radiated toward the receive antenna.

relation between effective aperture area and Directivity (gain)

The maximum effective aperture area of an antenna is related to the directivity of the antenna as,

$$A_e = \frac{D\lambda^2}{4\pi}$$

The maximum effective aperture area as defined above does not include the effect of losses in the antenna, which can be accounted for by replacing D with G , the gain, of the antenna.

$$A_e = \frac{G\lambda^2}{4\pi}$$

(l) Antenna Brightness temperature

When the antenna beamwidth is broad enough that different parts of the antenna pattern see different background temperatures, the effective brightness temperature seen by the antenna can be found by weighting the spatial distribution of background temperature by the pattern function of the antenna.

Mathematically we can write the brightness temperature T_b seen by the antenna as

$$T_b = \frac{\int_0^{2\pi} \int_{\theta=0}^{\pi} T_B(\theta, \phi) D(\theta, \phi) \sin\theta d\theta d\phi}{\int_0^{2\pi} \int_{\theta=0}^{\pi} D(\theta, \phi) \sin\theta d\theta d\phi}$$

Where $T_B(\theta, \phi)$ is the distribution of the background temperature, and $D(\theta, \phi)$ is the directivity (or the power pattern function) of the antenna. Antenna brightness temperature is referenced at the terminals of the antenna. Observe that when T_B is a constant, $T_b = T_B$

(m) Antenna Noise Temperature

If a receiving antenna has dissipative loss, so that its radiation efficiency η_{rad} is less than unity, the power available at the terminals of the antenna is reduced by the factor η_{rad} from that intercepted by the antenna (the definition of radiation efficiency is the ratio of output to input power).

This reduction applies to received noise power, as well as received signal power, so the noise temperature of the antenna will be reduced from the brightness temperature by the factor η_{rad} .

In addition, thermal noise will be generated internally by resistive losses in the antenna, and this will increase the noise temperature of the antenna. We can find the resulting noise temperature seen at the antenna terminals as,

$$T_A = \eta_{rad} T_b + (1 - \eta_{rad}) T_p$$

The equivalent temperature T_A is called the antenna noise temperature, and is a combination of the external brightness temperature seen by the antenna and the thermal noise generated by the antenna.

Note: This temperature is referenced at the output terminal of the antenna. $T_A =$

T_b for a lossless antenna with $\eta_{rad} = 1$.

If the radiation efficiency is zero, meaning that the antenna appears as a matched load and does not see any external background noise, then $T_A = T_p$, due to the thermal noise generated by the losses.

(n) G/T ratio

Useful figure of merit for receive antennas is the G/T ratio, defined as $10 \log(G/T_A)$ dB/K, where G is the gain of the antenna, and T_A is the antenna noise temperature.

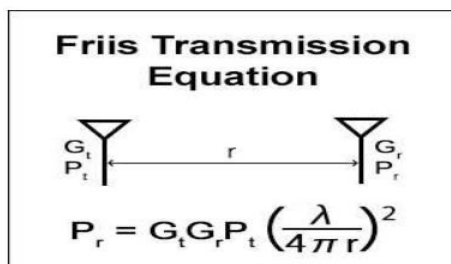
This quantity is important because, the signal-to-noise ratio (SNR) at the input to a receiver is proportional to G/T_A . The ratio G/T can often be maximized by increasing the gain of the antenna, since this increases the numerator and usually minimizes reception of noise from hot sources at low elevation angles. Of course, higher gain requires a larger and more expensive antenna, and high gain may not be desirable for applications requiring omnidirectional coverage (e.g., cellular telephones or mobile data networks), so often a compromise must be made.

Note: that the dimensions given for $10 \log(G/T)$ are not actually decibels per degree kelvin, but this is the nomenclature that is commonly used for this quantity

4(a) Derive Friis Transmission formula and explain its significance. (Apr/May'18)

Friis Transmission Formula

This formula gives the power received over a radiocommunication link.



Let the transmitter feed a power P_t to a transmitting antenna of effective aperture A_{et} . At a distance r a receiving antenna of effective aperture A_{er} , intercepts some of the power radiated by the transmitting antenna and delivers it to the receiver.

Assuming that the transmitting antenna is isotropic, the power per unit area at the receiving antenna is

$$S_r = \frac{P_t}{4\pi r^2} \quad (W) \text{-----1}$$

If the transmitting antenna has gain G_t , the power per unit area at the receiving antenna will be increased in proportion as given by,

$$S_r = \frac{P_t G_t}{4\pi r^2} \quad (W) \text{-----2}$$

Now, the power collected by the receiving antenna of effective aperture A_{er} is,

$$P_r = A_{er} S_r = \frac{A_{er} P_t G_t}{4\pi r^2} \quad (W) \quad 3$$

The gain of the transmitting antenna can be expressed as,

$$G_t = \frac{4\pi A_{et}}{\lambda^2} \quad \text{-----4a}$$

$$G_r = \frac{4\pi A_{er}}{\lambda^2} \quad \text{-----4b}$$

Substituting for gain in equation 3, we have,

$$P_r = \frac{A_{er} P_t A_{et} 4\pi}{4\pi r^2 \lambda^2} = \frac{A_{er} P_t A_{et}}{r^2 \lambda^2} \quad \text{-----5a}$$

In terms of antenna gain, received power can be expressed as,

$$P_r = \frac{G_r P_t G_t \lambda^2}{4\pi \times 4\pi r^2} = \frac{G_r P_t G_t \lambda^2}{(4\pi r)^2} \quad \text{-----5b}$$

Equation 5 is Friis transmission formula

$$P_r = \frac{G_r P_t G_t \lambda^2}{(4\pi r)^2}$$

(b) Explain in detail about Link budget and Link Margin..

Link Budget and Link Margin

The various terms in the Friis formula are often tabulated separately in a link budget, where each of the factors can be individually considered in terms of its net effect on the received power.

Additional loss factors, such as line losses or impedance mismatch at the antennas, atmospheric attenuation, and polarization mismatch can also be added to the link budget.

One of the terms in a link budget is the path loss, accounting for the free-space reduction in signal strength with distance between the transmitter and receiver.

Path loss = Transmitted power - Received power = $P_t - P_r$

Assuming unity gain antennas, path loss is given as (using Friis formula)

$$path\ loss\ (dB) = 20 \log \left(\frac{4\pi r}{\lambda} \right)$$

We can write the budget as shown in the following link budget:

Transmit power	P_t
Transmit antenna line loss	$(-)L_t$
Transmit antenna gain	G_t
Path loss (free-space)	$(-)L_0$
Atmospheric attenuation	$(-)L_A$
Receive antenna gain	G_r
Receive antenna line loss	$(-)L_r$
<hr/>	
Receive power	P_r

We have also included loss terms for atmospheric attenuation and line attenuation. Assuming that all of the above quantities are expressed in dB (or dBm, in the case of P_t), we can write the receive power as

$$P_r\ (dBm) = P_t - L_t + G_t - L_0 - L_A + G_r - L_r$$

If the transmit and/or receive antenna is not impedance matched to the transmitter/receiver (or to their connecting lines), impedance mismatch will reduce the received power by the factor $(1 - |\Gamma|^2)$ where Γ is the appropriate reflection coefficient.

The resulting impedance mismatch loss,

$$L_{imp}\ (dB) = -10 \log(1 - |\Gamma|^2) \geq 0,$$

can be included in the link budget to account for the reduction in received power.

Another possible entry in the link budget relates to the polarization matching of the transmit and receive antennas, as maximum power transmission between transmitter and receiver requires both antennas to be polarized in the same manner.

If a transmit antenna is vertically polarized, for example, maximum power will only be delivered to a vertically polarized receiving antenna, while zero power would be delivered to a horizontally polarized receive antenna, and half the available power would be delivered to a circularly polarized antenna.

Link Margin

In practical communications systems it is usually desired to have the received power level greater than the threshold level required for the minimum acceptable quality of service (usually expressed as the minimum carrier-to-noise ratio (CNR), or minimum SNR).

This design allowance for received power is referred to as the link margin, and can be expressed as the difference between the design value of received power and the minimum threshold value of receive power:

$$\text{Linkmargin (dB)} = LM = P_r - P_r(\text{min}) > 0, \text{ where all quantities are in dB.}$$

Link margin should be a positive number; typical values may range from 3 to 20 dB. Having a reasonable link margin provides a level of robustness to the system to account for variables such as signal fading due to weather, movement of a mobile user, multipath propagation problems, and other unpredictable effects that can degrade system performance.

Link margin for a given communication system can be improved by increasing the received power (by increasing transmit power or antenna gains), or by reducing the minimum threshold power (by improving the design of the receiver, changing the modulation method, or by other means)

Fade margin.

Signal fading occurs due to weather, movement of a mobile user, multipath propagation problems, and other unpredictable effects that can degrade system performance and quality of service. Link margin that is used to account for fading effects is sometimes referred to as fade margin.

5. Explain in detail about Noise characterization of a microwave receiver.

Noise Characterization of a Microwave Receiver

(i) NOISE FIGURE and EQUIVALENT NOISE TEMPERATURE of a SYSTEM

(General concepts)

The signal-to-noise ratio is the ratio of desired signal power to undesired noise power, and so is dependent on the signal power.

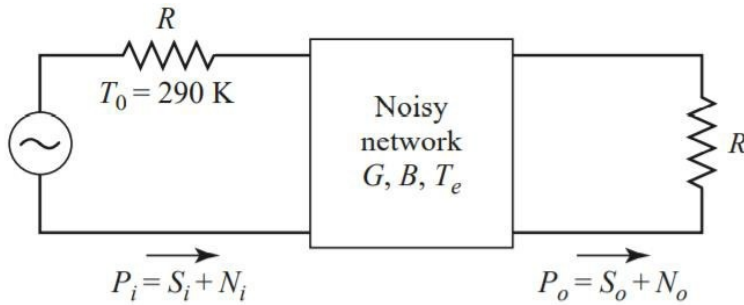
When noise and a desired signal are applied to the input of a noiseless network, both noise and signal will be attenuated or amplified by the same factor, so that the signal-to-noise ratio will be unchanged.

However, if the network is noisy, the output noise power will be increased more than the output signal power, so that the output signal-to-noise ratio will be reduced.

The noise figure, F , is a measure of this reduction in signal-to-noise ratio, and is defined as,

$$F = \frac{S_i/N_i}{S_o/N_o} \geq 1 \text{-----(1)}$$

where S_i , N_i are the input signal and noise powers, and S_o , N_o are the output signal and noise powers. By definition, the input noise power is assumed to be the noise power resulting from a matched resistor at $T_0 = 290$ K; that is, $N_i = kT_0B$.



Determining the noise figure of a noisy network.

Consider Figures shown above, which shows noise power N_i and signal power S_i being fed into a noisy two-port network.

The network is characterized by a gain, G , a bandwidth, B , and an equivalent noise temperature, T_e .

The input noise power is $N_i = kT_0B$, and the output noise power is a sum of the amplified input noise and the internally generated noise: $N_o = kGB(T_0 + T_e)$.

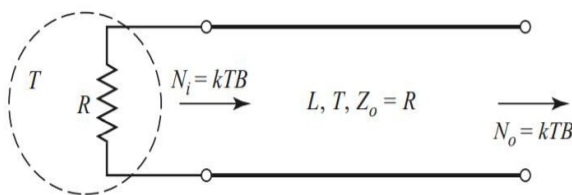
The output signal power is $S_o = GS_i$. Using these results in (1) gives the noise figure as,

$$F = \frac{S_i}{kT_0B} \times \frac{kGB(T_0 + T_e)}{GS_i} = 1 + \frac{T_e}{T_0} \geq 1 \text{-----(2)}$$

$$T_e = (F - 1)T_0 \text{-----(3)}$$

It is important to keep in mind two things concerning the definition of noise figure: noise figure is defined for a matched input source, and for a noise source equivalent to a matched load at temperature $T_0 = 290$ K. Noise figure and equivalent noise temperatures are interchangeable characterizations of the noise properties of a component.

An important special case occurs in practice for a two-port network consisting of a passive, lossy component, such as an attenuator or lossy transmission line, held at a physical temperature T . Consider such a network with a matched source resistor that is also at temperature T , as shown in Figure



Determining the noise figure of a lossy line or attenuator with loss L and temperature T .

The power gain, G , of a lossy network is less than unity; the loss factor, L , can be defined as $L = 1/G > 1$. Because the entire system is in thermal equilibrium at the temperature T , and has a driving point impedance of R , the output noise power must be $N_o = kTB$. However, we can also think of this power as coming from the source resistor (attenuated by the lossy line), and from the noise generated by the line itself. Thus we also have that

$$N_o = kTB = GkTB + GN_{added} \text{-----(4)}$$

Where N_{added} is the noise generated by the line, as if it appeared at the input terminals of the line. Solving (4) for this power gives

$$N_{added} = \frac{(1-G)}{G} kTB = (L-1)kTB \text{-----(5)}$$

Then (5) shows that the lossy line has an equivalent noise temperature (referred to the input) given by,

$$T_e = (L-1)T \text{-----(6)}$$

Noise figure is,

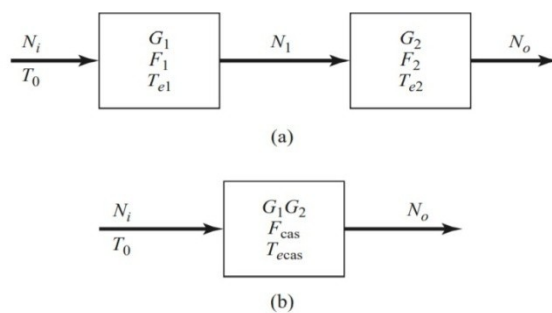
$$F = \frac{T_e + T}{T} \geq 1 \text{-----(7)}$$

Noise Figure of a Cascaded System

In a typical microwave system the input signal travels through a cascade of many different components, each of which may degrade the signal-to-noise ratio to some degree. If we know the noise figure (or noise temperature) of the individual stages, we can determine the noise figure (or noise temperature) of the cascade connection of stages.

We will see that the noise performance of the first stage is usually the most critical, an interesting result that is very important in practice.

Consider the cascade of two components, having gains G_1, G_2 , noise figures F_1, F_2 , and equivalent noise temperatures T_{e1}, T_{e2} , as shown in Figure.



Noise figure and equivalent noise temperature of a cascaded system. (a) Two cascaded networks. (b) Equivalent network.

We wish to find the overall noise figure and equivalent noise temperature of the cascade, as if it were a single component. The overall gain of the cascade is $G_1 G_2$.

Using noise temperatures, we can write the noise power at the output of the first stage as $N_1 =$

$$G_1 k T_0 B + G_1 k T_{e1} B \text{-----(8)}$$

since $N_i = k T_0 B$ for noise figure calculations. The noise power at the output of the second stage is

$$N_o = G_2 N_1 + G_2 k T_{e2} B$$

$$N_o = G_1 G_2 k T_o B + G_1 G_2 k T_{e1} B + G_2 k T_{e2} B$$

$$N_o = G_1 G_2 k B \left(T_o + T_{e1} + \frac{T_{e2}}{G_1} \right) \text{-----(9)}$$

For the equivalent system we have,

$$N_o = G_1 G_2 k B (T_o + T_{cas}) \text{-----(10)}$$

Where,

$$T_{cas} = T_{e1} + \frac{T_{e2}}{G_1} \text{-----(11)}$$

Using (3) to convert the temperatures in (11) to noise figures yields the noise figure of the cascade system as,

$$F_{cas} = F_1 \frac{(F_2 - 1)}{G_1} \text{-----(12)}$$

Equations (11) and (12) show that the noise characteristics of a cascaded system are dominated by the characteristics of the first stage since the effect of the second stage is reduced by the gain of the first (assuming $G_1 > 1$).

Thus, for the best overall system noise performance, the first stage should have a low noise figure and at least moderate gain. Expense and effort should be devoted primarily to the first stage, as opposed to later stages, since later stages have a diminished impact on the overall noise performance.

Equations (11) and (12) can be generalized to an arbitrary number of stages, as

(ii) **Noise Characterization of Receiver**

We can now analyze the noise characteristics of a complete antenna–transmission line–receiver front end, as shown in Figure. In this system the total noise power at the output of the receiver, N_o , will be due to contributions from the antenna pattern, the loss in the antenna, the loss in the transmission line, and the receiver components.

This noise power will determine the minimum detectable signal level for the receiver and, for a given transmitter power, the maximum range of the communication link.

The transmission line connecting the antenna to the receiver has a loss L_T , and is at a physical temperature T_p .

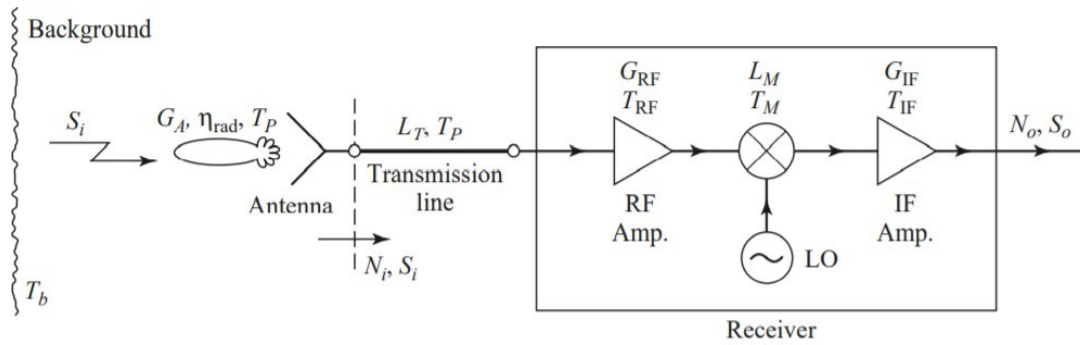


FIGURE 14.14 Noise analysis of a microwave receiver front end, including antenna and transmission line contributions.

The receiver components in Figure consist of an RF amplifier with gain G_{RF} and noise temperature T_{RF} , a mixer with loss L_M and noise temperature T_M , and an IF amplifier with gain G_{IF} and noise temperature T_{IF} .

The noise effects of later stages can usually be ignored since the overall noise figure is dominated by the characteristics of the first stage. The component noise temperatures can be related to noise figures as $T = (F - 1)T_0$. The equivalent noise temperature

$$T_{RECEIVER} = T_{RF} + \frac{T_M + T_{IF} L_M}{G_{RF} G_{IF}} \quad (1)$$

So, its equivalent noise temperature is

$$T_{TL} = (L_T - 1)T_p \quad (2)$$

We can find that the noise temperature of the transmission line (TL) and receiver (REC) cascade is

$$T_{TL+REC} = T_{TL} + L_T T_{RECEIVER} = (L_T - 1)T_p + L_T T_{RECEIVER} \quad (3)$$

This noise temperature is defined at the antenna terminals (the input to the transmission line). The entire antenna pattern can collect noise power. If the antenna has a reasonably high gain with relatively low sidelobes, we can assume that all noise power comes via the main beam, so that the noise temperature of the antenna is given by,

$$T_A = \eta_{rad} T_b + (1 - \eta_{rad}) T_p \quad (4)$$

where η_{rad} is the efficiency of the antenna, T_p is its physical temperature, and T_b is the equivalent brightness temperature of the background seen by the main beam.

The noise power at the antenna terminals, which is also the noise power delivered to the transmission line, is

$$N_i = kBT_A = kB[\eta_{rad}T_b + (1 - \eta_{rad})T_p] \text{-----(5)}$$

where B is the system bandwidth. If S_i is the received power at the antenna terminals, then the input SNR at the antenna terminals is S_i/N_i .

The output signal power is,

$$S_o = \frac{S_i G_{RF} G_{IF}}{L_{TLM}} = S_i G_{iSYS} \text{-----(6)}$$

where G_{SYS} has been defined as a system power gain. The output noise power is,

$$N_o = (N_i + kBT_{TL+REC}) G_{SYS}$$

$$N_o = (kBT_A + kBT_{TL+REC}) G_{SYS}$$

$$N_o = kB(T_A + T_{TL+REC}) G_{SYS} = kBT_{SYS} G_{SYS} \text{... (7)}$$

where T_{SYS} has been defined as the overall system noise temperature

